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BE IT KNOWN that I, Minoru FUKUDA, a citizen of Japan, residing at 3-7-3, Futako, Takatsu-ku, Kawasaki-shi, Kanagawa, Japan, have made a new and useful improvement in "SHEET CONVEYING DEVICE WITH A SHEET STORAGE" of which the following is the true, clear and exact specification, reference being had to the accompanying drawings.

There has been proposed a sheet conveying device of  
20 the type including a roll-up sheet storage capable of

rolling up an elongate sheet discharged and storing it in the form of a roll. This type of sheet conveying device may be constructed to allow the operator of the device to pick up the sheet from the roll-up sheet storage at the front of the device while, e.g., correcting a skew at the same side of the device.

A sheet conveying device with a roll-up sheet storage is taught in, e.g., Japanese Patent Laid-Open Publication No. 10-305956. The device taught in this document includes first stocking means, second stocking means, and guiding means. The first stocking means is partly openable for storing a sheet by rolling it up while the second stocking means stores a sheet in a straight position. The guiding means is positioned in the vicinity of outlet rollers for selectively steering a sheet toward either one of the first and second stocking means in accordance with the length of the sheet. The operator of the device opens part of the first stocking means in order to pick up the rolled sheet. However, the guiding means adjoining the outlet rollers, i.e., an outlet brings about the following problem. When the operator picks up the rolled sheet stored in the first stocking means, the trailing edge of the sheet is apt to contact the casing of the device, which forms a guide path, and be damaged thereby.

Technologies relating to the present invention are



FIG. 1 is a perspective view showing a first embodiment of the sheet conveying device in accordance with the present invention;

FIG. 3 is a view similar to FIG. 2, showing the device open position;

FIG. 5 is a flowchart demonstrating a specific  
tion of the first embodiment;

15           FIG. 7 is a schematic block diagram showing a control  
system included in the second embodiment;

FIG. 9 is a side elevation showing a third embodiment of the present invention;

FIGS. 11A and 11B are fragmentary views showing a fifth embodiment of the present invention;

25            FIG. 12 is a side elevation showing a sixth

embodiment of the present invention;

FIG. 13 is a fragmentary enlarged view showing a mechanism included in the sixth embodiment for rotating a roll-up guide;

5        FIG. 14 is a fragmentary enlarged view showing a specific condition wherein a relatively thick sheet has failed to rise along the inner periphery of a guide and collapsed;

10        FIGS. 15A through 15C are views showing an anti-twist mechanism included in a seventh embodiment of the present invention;

FIG. 16 is a view showing an anti-twist mechanism representative of an eighth embodiment of the present invention; and

15        FIGS. 17A and 17B are views showing an anti-twist mechanism representative of a ninth embodiment of the present invention.

#### DESCRIPTION OF THE PREFERRED EMBODIMENTS

20        Preferred embodiments of a sheet conveying device in accordance with the present invention will be described hereinafter.

##### First Embodiment

25        Referring to FIGS. 1 through 3 of the drawings, a sheet conveying device embodying the present invention is

shown will be described. As shown, the sheet conveying device conveys a sheet (document) S to a reading position and then delivers it to a particular destination in accordance with a mode selected, i.e., a rear discharge mode, a front discharge mode or a roll-up mode. In the rear discharge mode, the device delivers the sheet S having been read to a first tray 26 mounted on the rear (back) thereof. In the front discharge mode, the device delivers the sheet S to a second tray 12 mounted on the front part thereof. Further, in the roll-up mode, the device causes a roll-up guide 27 to roll up the sheet S being delivered toward the first tray 26. After the sheet S has been rolled up by the roll-up guide 27, the operator of the device angularly moves the guide 27 upward in order to pick up the rolled sheet S from the top or the side of the guide 27.

Specifically, the illustrative embodiment is generally made up of an upper unit 100 and a lower unit 200. The upper unit 100 is hinged to the lower unit 200 in such a manner as to be movable toward and away from the lower unit 200. An operation panel 11 and the second tray 12 are mounted on the top of the upper unit 100 and oriented toward the front where the operator is expected to stand. The roll-up guide 27 is mounted on the rear end of the top of the upper unit 100 such that it can be angularly moved

by hand between the top and the back of the upper unit 100.

The roll-up guide 27 is connected to the upper unit 100 by connecting means including a support member that supports a shaft 29, so that the guide 27 can be rotated about the shaft 29. More specifically, the operator may operate a knob 28 in order to move the roll-up guide 27 between a roll-up position and a pick-up position. The roll-up position is defined at the rear of the device and adjoins a sheet outlet downstream of a pair of rollers 14a and 14b. The pick-up position is defined above (front side) the device. At the pick-up position, the top of the upper unit 100 plays the role of a stop for restricting the angular movement of the roll-up guide 27 and thereby maintains a preselected distance between the guide 27 and the second tray 12.

The roll-up guide 27 is made up of a hollow cylindrical portion partly open in the direction of length thereof (direction of width of the sheet S) and a Mylar sheet affixed to one edge of the cylindrical portion. The inner periphery of the cylindrical portion has an arcuate cross-section. The Mylar sheet blocks part of the opening of the cylindrical portion (including the sheet inlet) when the sheet S is rolled up or unblocks the above opening when the rolled sheet S is to be picked up. The inside diameter of the cylindrical portion is selected to be about



5 More specifically, the cylindrical portion of the roll-up guide 27 is implemented by a member formed of plastics and a wire, or guide rod, formed of metal. The wire is configured in the form of the teeth of a comb. In the roll-up position, the wire intersects a wire or guide rod mounted on the first tray 26 and also configured as the teeth of a comb. In addition, the wire in the roll-up position abuts against a wire-like stop 25 mounted on the first tray 26.

20 A group of keys 31, including a start key and numeral keys, and an LCD (Liquid Crystal Display) or similar display 32 are arranged on the operation panel 11. The operator may set a desired mode and start and stop the operation of the device via the keys 31. Commands input  
25 on the keys 31 are sent to a controller 41 (see FIG. 4),

which will be described specifically later. A reading section or scanner unit 17 includes mirrors, a light source, a lens, a shading plate, a CCD (Charge Coupled Device) image sensor or similar photoelectric transducer, and a scanner motor although not shown specifically. When the sheet or document S inserted into the front of the device is conveyed along a preselected path, the reading section 17 illuminates the sheet S from above the path. The resulting reflection from the sheet S is incident to the photosensitive surface of the photoelectric transducer via the mirrors and lens. The transducer transforms the incident imagewise light to a corresponding electric image signal (image data).

A first discharge sensor 19 is a reflection type sensor located upstream of the rollers 14a and 14b, which are, in turn, positioned upstream of a path selector 22. The discharge sensor 19 turns on when the leading edge of the sheet S reaches the rollers 14a and 14b, and then turns off when the trailing edge of the sheet S moves away from the rollers 14a and 14b. When the discharge sensor 19 turns off in the roll-up mode, there are executed the return of the path selector 22 and the stop of a conveyance motor 43 (see FIG. 4).

A solenoid, not shown, actuates the path selector 22 in accordance with the mode selected. Specifically,

in the front discharge mode, the solenoid maintains the path selector 22 at a home position indicated by a phantom line in FIG. 2. In this position, the path selector 22 steers the sheet S toward a second sheet guide 21. In the rear discharge mode and roll-up mode, the solenoid brings the path selector to a position indicated by a solid line in FIG. 2, so that the sheet S is steered toward the first tray 26.

A Mylar sheet 23 is fitted to the edge of the path selector 22 adjoining the sheet outlet, and extends in the widthwise direction of the sheet S. In the roll-up mode, the Mylar sheet 23 cooperates with the first tray 26 to guide the sheet S such that the sheet S surely enters the inlet of the roll-up guide 27 without any curl. If desired, the Mylar sheet 23 may be replaced with an extension extending from the path selector 22 toward the downstream side. In such a case, the extension and Mylar sheet 24 both are configured like the teeth of a comb in order to prevent the former from contacting the latter.

A second discharge sensor 20 is a reflection type sensor located upstream of a pair of rollers 15a and 15b. The discharge sensor 20 turns on when the leading edge of the sheet S reaches the rollers 15a and 15b located downstream of the path selector 22, and then turns off when the trailing edge of the sheet S moves away from the rollers

15a and 15b. On the turn-off of the discharge sensor 20 in the front discharge mode, the conveyance motor 43 is deenergized.

5 A sheet table 30 is mounted on the top of the front portion of the lower unit 200. The first tray 26 protrudes rearward from the rear end of the lower unit 200. When the sheet or document S is laid on the sheet table 30 face up and inserted in a direction a, the table 30 guides the sheet S to a nip between a pair of rollers 13a and 13b.

10 A registration sensor 18 is a reflection type sensor located upstream of the reading section 17. The registration sensor 18 turns on when the leading edge of the sheet S reaches the reading section 17, and then turns off when the trailing edge of the sheet S moves away from  
15 the reading section 17. When the registration sensor 18 turns off in the rear discharge mode, there are executed the return of the path selector 22 and the stop of the conveyance motor 43.

20 The first tray 26 is inclined upward from the rear end of the lower unit 200 and implemented by a metallic wire configured like the teeth of a comb. The first tray 26 receives the sheet S being driven out in a direction d via a sheet outlet, which is located downstream of the rollers 14a and 14b. When the roll-up guide 27 is located  
25 at the roll-up position, the comb-like wire of the first

tray 26 and that of the roll-up guide intersect each other. In this condition, part of the first tray 26 serves as an inlet (guiding means) to the roll-up guide 27.

A rod-like stop (metallic wire) 25 extends on the first tray 26 in the widthwise direction of the sheet S. The stop 25 is inclined upward from the front to the rear in the direction of paper conveyance relative to the upper surface (wire) of the first tray 26. The stop 25 therefore intersects the wire of the tray 26. When the tray 26 and the roll-up guide 27 intersect each other, the wire of the guide 27 abuts against the inclined surface of the stop 25 and is restricted thereby.

As shown in FIG. 3, assume that the operator of the device opens the upper unit 100 away from the lower unit 15 200 in order to, e.g., remove a jamming sheet. Then, the roll-up guide 27 rotates about the shaft 29 with the result that the wire of the guide 27 slides to the right, as seen in FIG. 3, on the inclined surface of the stop 25. Consequently, the cylindrical portion of the guide 27 20 maintains its arcuate configuration. At this instant, the cylindrical portion moves slightly downward and causes the Mylar sheet 24 to contact the tray 26 and deform. However, the sheet S does not deform because of the elasticity of the Mylar sheet 24. The Mylar sheet 24 should preferably 25 be positioned on a normal line inclined by an angle of 40

25 be positioned on a normal line inclined by an angle of 40

degrees or above relative to a vertical line extending downward from the shaft 29. Should the above angle be smaller than 40 degrees, the stop 25 would deform or fail to smoothly slide on contacting the roll-up guide 27.

5           The conveyance motor 43 reversibly drives the rollers 13b, 14b and 15b and a backup roller 16, which faces the reading section 17. The conveyance motor 43 is implemented by a stepping motor and applied with a source voltage from the device body. The rollers 13a, 14a and  
10   15a are driven rollers cooperative with the rollers 13b, 14b and 15b for conveying the sheet S.

Referring to FIG. 4, the sensors 18 through 20, conveyance motor 43 and operation panel 11 are connected to the controller 41. The controller 41 executes various  
15   processing, e.g., controls the drive of the motor 43 (including speed control) and controls the display 32 in accordance with the outputs of the above constituents. The controller 41 includes a RAM (Random Access Memory)  
20   42 for storing the instantaneous operation modes, which include the front discharge, rear discharge or roll-up mode. Data stored in the RAM 42 are updated every time any one of the modes is replaced with another mode.

Assume that the above-described sheet conveying device is mounted on an image forming apparatus. Then,  
25   the illustrative embodiment additionally includes a

photoconductive drum, an image forming section, a sheet conveying section, and a sheet receiving section. The image forming section includes a charger, a developing device, image transferring and sheet separating device, a cleaning device and a discharger arranged around the photoconductive drum. The sheet conveying section conveys a paper sheet or similar recording medium toward the drum at a preselected timing. The sheet receiving section receives the paper sheet.

Reference will be made to FIG. 5 for describing a specific sheet discharging operation particular to the illustrative embodiment. As shown, assume that the operator selects the rear discharge mode on the operation panel 11 (YES, step S101). Then, the controller 41 causes the previously mentioned solenoid to pull the path selector 22 and retract it from the home position (step S102). The controller 41 then drives the conveyance motor 43 such that the rollers 13a, 13b, 14a and 14b and backup roller 16 rotate forward (step S103). In this condition, the sheet S inserted in the direction a face up is conveyed to the reading section 17. After the sheet S has been read by the reading section 17, it is simply driven out of the device to the first tray 26 via the sheet outlet adjoining the path selector 22.

When the trailing edge of the sheet moves away from

the reading section 17, the registration sensor 18 turns off and sends its output to the controller 41. In response, the controller 41 determines whether or not t1 seconds have elapsed since the receipt of the output of the sensor 18 (step S104). If the answer of the step S104 is YES, the controller 41 returns the path selector 22 to the home position (step S105) and then deenergizes the conveyance motor 43 (step S106).

In the rear discharge mode, the operator is expected to turn the roll-up guide 27 to the roll-up position above the device via the knob 28. Therefore, the roll-up guide 27 and first tray 26 do not intersect each other, allowing the sheet S to reach the tray 26 in a straight position.

On the other hand, assume that the operator selects the roll-up mode on the operation panel (N0, step S101 and YES, step S107). Then, the controller 41 causes the solenoid to retract the path selector 22 from the home position (step S108). The controller 41 then causes the conveyance motor 43 to rotate the rollers 13a, 13b, 14a and 14b and backup roller 16 forward (step S109). As a result, the sheet S inserted in the direction a face up is conveyed to the reading section 17.

After the sheet S has been read by the reading section 17, it is discharged to the first tray 26 via the sheet outlet adjoining the path selector 22. At this instant,



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of the step S114 is YES, the controller 41 deenergizes the conveyance motor 43 (step S115).

As stated above, the illustrative embodiment selectively reverses an elongate sheet, which is frequently used, and discharges it to the rear, or rolls up such a sheet and stores it in a compact configuration, or simply discharged a relatively thick, elongate sheet in a straight position. The operator can select any one of such processing in accordance with the thickness, length, width and so forth of a sheet. Particularly, in the roll-up mode, the illustrative embodiment allows the operator, standing at the front of the device, to pick up the rolled sheet from the above or the side of the roll-up guide 27 without damaging the sheet.

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#### Second Embodiment

A second embodiment of the present invention will be described with reference to FIGS. 6 and 7. Structural elements identical with the structural elements of the first embodiment are designated by identical reference numerals and will not be described specifically. As shown, the illustrative embodiment additionally includes a switch or sensor 33 for sensing the roll-up guide 27 brought to its roll-up position. Specifically, the switch 33 turns on when the roll-up guide 27 is positioned by the stop 25 and contacts the back of the upper unit 100 at one

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end thereof. The switch 33 turns off when the roll-up guide 27 is moved to its pick-up position and contacts the top of the upper unit 100 at the other end thereof. As shown in FIG. 7, the switch 33 is connected to the controller 41. Assume that in the rear discharge mode, the roll-up guide 27 is held at the roll-up position, as indicated by the output of the switch 33. Then, the controller 41 controls the conveyance motor 43 such that the rollers 14a and 14b nip the trailing edge of the sheet S being driven out to the first tray 25.

A specific operation of the illustrative embodiment will be described with reference to FIG. 8. As shown, assume that the switch 33 is in an OFF state (NO, step S201) and that the rear discharge mode is selected (YES, step S202). Then, the controller 41 retracts the path selector 22 from the home position (step S208) and causes the conveyance motor 43 to rotate forward (step S209), as in the previous embodiment. Consequently, the sheet S inserted in the direction a is conveyed to the reading section 17 and then driven out to the first tray 26 face up in a straight position.

The controller 14 determines whether or not t4 seconds have passed since the registration sensor 18 sensed the trailing edge of the sheet S (step S210). If the answer of the step S210 is YES, the controller 41

deenergizes the conveyance motor 43 while maintaining the path selector 22 in the retracted position (step S211). In the illustrative embodiment, at the time when the motor 43 is deenergized, the rollers 14a and 14b nip the trailing edge of the sheet S. This allows the sheet S to be surely received by the first tray 26, i.e., prevents it from dropping from the tray 26.

On the other hand, assume that the switch 33 is in an ON state (YES, step 201) and that the roll-up mode is selected (YES, step S212). Then, the controller 41 retracts the path selector 22 from the home position (step S213) and causes the conveyance motor 43 to rotate forward (step S214). Consequently, the sheet S inserted in the direction a is conveyed to the reading section 17 and then guided toward the first tray 26 face up in a straight position. The sheet S is further guided to the inlet of the roll-up guide 25 that is positioned by the stop 25 and intersecting the first tray 26. As a result, the sheet S is rolled up with its image surface positioned inside and stored in the roll-up guide 27 in the form of a roll.

Subsequently, the controller 41 determines whether or not  $t_2$  seconds have passed since the first discharge sensor 19 sensed the trailing edge of the sheet S (step S215). If the answer of the step S215 is YES, the controller 41 returns the path selector 22 to the home

position (step S216) and then deenergizes the conveyance motor 43 (step S217), as in the previous embodiment.

Further, assume that the switch 33 is in an OFF state (NO, step S201) and that the front discharge mode is selected (NO, step 202 and YES, step S203). Then, the controller 41 causes the conveyance motor 43 to rotate forward (step S204) while maintaining the path selector 22 at the home position. Consequently, the sheet S inserted in the direction a is conveyed to the reading section 17 and then reversed by the second guide 21 to be driven out to the second tray 12 face down.

The controller 41 then determines whether or not t3 seconds have passed since the second discharge sensor 20 sensed the trailing edge of the sheet S (step S205). If the answer of the step S205 is YES, the controller 41 deenergizes the conveyance motor 43 (step S206).

Assume that the switch 33 is in an OFF state (NO, step S201), but neither one of the front and rear discharge modes is selected (NO, step S202 and NO, step S203), or that the switch 33 is in an ON state (YES, step S201), but the take-up mode is not selected (NO, step S212). Then, the controller 41 displays on the display 32 an alarm message informing the operator of the fact that the position of the roll-up guide 27 and the operation mode do not match (step S207 or S218).

### Third Embodiment

A third embodiment of the present invention will be described with reference to FIG. 9. Structural elements identical with the structural elements of the first  
5 embodiment are designated by identical reference numerals and will not be described specifically in order to avoid redundancy. As shown, an endless belt 37 extends between a position around the upstream end of the first tray 26 and a position around the stop 25. A motor, not shown,  
10 drives the belt 37 and is applied with a power source voltage from the device body like the conveyance motor 43.

In the roll-up mode, when a preselected period of time elapses since the first discharge sensor 19 sensed the trailing edge of the sheet S, the controller 41, not  
15 shown, energizes the motor not shown. The motor causes the belt 37 to turn in the direction in which the sheet S is driven out to the first tray 26. The belt 37 therefore conveys the sheet S contacting the belt 37, while backing up the sheet S. This allows the Mylar sheet 23 and first  
20 tray 26 to surely guide the sheet S up to the inlet of the roll-up guide and thereby prevents the trailing edge of the sheet S from remaining in the portion around the outlet.

It is to be noted that the above-described configuration is similarly applicable to the first and  
25 second embodiments.

Fourth Embodiment

FIG. 10 shows a fourth embodiment of the present invention. Structural elements identical with the structural elements of the first embodiment are designated by identical reference numerals and will not be described specifically in order to avoid redundancy. As shown, the reading section 17 is mounted on the lower unit 200 and reads the sheet S inserted face down in the direction a. The roll-up guide 27 rolls up the sheet S in accordance with the direction of image reading with the image surface of the sheet S being positioned inside.

A first tray 34 protrudes rearward from the lower unit 200 and can be folded downward at a position around the outlet. The roll-up guide 27, which is angularly movable about the shaft 29, is selectively brought to a roll-up position around the bendable portion of the first tray 23 or a pick-up position above the upper unit 100. The back and top of the upper unit 100 respectively serve as a stop in the roll-up position and pick-up position of the roll-up guide 27, restricting the movement of the guide 27.

The roll-up guide 27 is made up of the hollow cylindrical portion and Mylar sheet 24. The cylindrical portion is partly open in the lengthwise direction, i.e., the widthwise direction of the sheet S. The Mylar sheet



24 is fitted on one edge of the cylindrical portion in such a manner as to block part of the opening of the cylindrical portion (including the inlet). In the illustrative embodiment, the Mylar sheet 24 protrudes toward the position around the foldable portion of the first tray 34 so as to guide the sheet S to be rolled toward the bottom of the inner periphery of the cylindrical portion.

In the roll-up mode, the operator folds the first tray 34 downward in order to prevent it from interfering with the roll-up guide 27. At the same time, part of the first tray 34 plays the role of a guide for guiding the sheet S toward the inlet of the roll-up guide 27.

In the illustrative embodiment, in the roll-up mode, the controller 41 accelerates the conveyance of the sheet S to the maximum speed at a preselected timing after the first discharge sensor 19 has sensed the trailing edge of the sheet. This acceleration is similarly applicable to the first and second embodiments.

How the illustrative embodiment discharges the sheet S in the roll-up mode will be described hereinafter. In the roll-up mode, the controller 41 retracts the path selector 22 from the home position and causes the conveyance motor 43 to rotate the rollers 13a, 13b, 14a and 14b forward. In this condition, the sheet S inserted in the direction a face down is conveyed to the reading

section 17.

After the sheet S has been read by the reading section 17, it is discharged face down via the outlet adjoining the path selector 22. Part of the first tray 34 and Mylar sheet 24 guide the sheet S coming out of the outlet to the inlet of the roll-up guide 27. At this instant, the Mylar sheet 23 fitted on the path selector 22 prevents the sheet S from curling or entering the gap between the Mylar sheet 24 and the support member of the roll-up guide 27.

The leading edge of the sheet S entered the roll-up guide 27 moves downward along the arcuate inner periphery of the guide 27, then rises, and then falls due to its own weight. By repeating such a motion, the sheet S is rolled up and stored in the roll-up guide 27 with the image surface position inside. At the time when the sheet S is fully rolled up, the trailing edge of the sheet S still remains in the casing, i.e., between the outlet and the rollers 14a and 14b. The operator therefore moves the roll-up guide 27 from the roll-up position to the pick-up position, thereby spacing the trailing edge of the sheet from the casing. The user, standing at the front of the device, picks up the rolled sheet S from the above or the side of the roll-up guide 27.

When the first discharge sensor 19 senses the passage of the trailing edge of the sheet S, the controller 41

increases the sheet conveying speed to the preselected maximum speed. On the elapse of a preselected period of time since the turn-off of the sensor 19, the controller 41 returns the path selector 22 to the home position and stops driving the conveyance motor 43.

#### Fifth Embodiment

FIG. 11 shows a fifth embodiment of the present invention. Structural elements identical with the structural elements of the first embodiment are designated by identical reference numerals and will not be described specifically in order to avoid redundancy. As shown, a roll-up storage 35 protrudes from the top of the device in order to store the sheet S while rolling it up in the roll-up mode. The sheet S is rolled up and then picked up at the same position adjacent to the operator. The roll-up storage 35 is generally made up of an outside guide 35a, an inside guide 35b, and a hollow cylinder 35c. The outside guide 35a and cylinder 35c play the role of a tray assigned to the front discharge mode at the same time. This tray corresponds to the second tray 12 shown in FIG. 1.

Specifically, the outside guide 35a and inside guide 35b cooperate to guide the sheet S reversed by the second discharge guide 21 and then conveyed by the rollers 15a and 15b into the cylinder 35c. The sheet S is rolled up

and stored in the cylinder 35c. The cylinder 35c is open at opposite ends thereof in the widthwise direction of the sheet S. The leading edge of the sheet S entered the cylinder 35c rises along the arcuate inner periphery of the cylinder 35c due to the conveying force of the rollers 15a and 15b and then falls due to its own weight. By repeating such a motion, the sheet S is rolled up and stored in the cylinder 35c. The roll-up storage 35 is angularly movable about the shaft 29 between a roll-up position and a front discharge position.

In the front discharge mode and roll-up mode, a solenoid mechanism, not shown, maintains a path selector 36 in a home position shown in FIGS. 11A and 11B. In the home position, the path selector 36 steers the sheet S toward the second discharge guide 21. In the rear discharge mode, the solenoid mechanism retracts the path selector 36 from the home position to a position above the conveyance path, so that the sheet S can be driven out to the first tray 26 in a straight position.

In the roll-up mode, the sheet S being conveyed by the rollers 15a and 15b enters a gap between the outside guide 35a and the inside guide 35b. In the front discharge mode, the sheet S is discharged along the outer periphery of the outside guide 35a and cylinder 35c. The operator is expected to so switch the position of the outside guide

35a and inside guide 35b.

In operation, in the roll-up mode, the path selector 36 is held in the home position while the roll-up storage 35 is held in the position shown in FIG. 11A. The sheet S is reversed by the second discharge guide 21 and then guided into the cylinder 35c by the outside guide 35a and inside guide 35b. Consequently, the sheet S is rolled up in the cylinder 35c, as stated earlier. At the time when the sheet S is fully rolled up, the trailing edge of the sheet S still remains between the outside guide 35a and the inside guide 35b. The operator therefore turns the sheet roll through the opposite open ends of the cylinder 35c in order to fully roll up the remaining portion of the sheet S. The operator then takes out the rolled sheet S via either one of the opposite ends of the cylinder 35c.

In the front discharge mode, the path selector 36 is held at the home position while the roll-up storage 35 is located at the position shown in FIG. 11B. The sheet S is reversed by the second discharge guide 21 and then discharged along the outer periphery of the outside guide 35a and cylinder 35c.

In the rear discharge mode, the path selector 36 is retracted upward while the roll-up storage 35 is located at the position shown in FIG. 11A or 11B. The sheet S is driven out to the first tray 26 via the path selector 36

in a straight position.

#### Sixth Embodiment

Referring to FIGS. 12 and 13, a sixth embodiment of the present invention will be described. Structural elements identical with the structural elements of the first embodiment are designated by identical reference numerals and will not be described specifically in order to avoid redundancy. As shown, the illustrative embodiment includes a lever 50 rotatable in contact with the roll-up guide 27 and a sensor 53 responsive to the position of the lever 50.

In the illustrative embodiment, the roll-up guide 27 starts rolling the sheet S at a particular position in accordance with the thickness of the sheet S. Specifically, the roll-up guide 27 starts rolling a relatively thin, soft sheet at a position indicated by a solid line in FIG. 13 or starts rolling a relatively thick, hard sheet at a position indicated by a dotted line in FIG. 13. The relatively thin sheet refers to plain sheets whose weight is, e.g., 52.3 g/m<sup>2</sup> or below while the relatively thick sheets refers to plain sheets whose weight is up to, e.g., 127.9 g/m<sup>2</sup>. The position indicated by the dotted line provides the roll-up guide 27 with a broader roll-up space than the position indicated by the solid line. Stated another way, the roll-up guide 27 is provided with

a greater inscribed circle when rolling up a thick sheet than when rolling up a thin sheet.

More specifically, assume that the inscribed circle is excessively large when the roll-up guide 27 rolls a thin sheet. Then, the sheet fails to fully rise along the inner periphery of the guide 27 and collapses in a folded position, as shown in FIG. 14. On the other hand, assume that the inscribed circle is excessively small when the roll-up guide 27 rolls a thick sheet. Then, the diameter of the sheet (roll) being rolled increases and exerts pressure on the guide 27, increasing frictional resistance between the sheet and the guide 27. As a result, the sheet is apt to bend in the form of bellows and jam the guide 27. In light of the above, the lever 50 is rotated to angularly move the guide 27 and cause the guide 27 to start rolling a sheet at either one of the two preselected positions. The guide 27 is further moved in accordance with the progress of the rolling operation, as will be described specifically later.

As shown in FIG. 13, a gear 51 is mounted on the same shaft as the lever 50. A lever motor 54, which is implemented by a stepping motor, has an output shaft operatively connected to the gear 51 via a gear 52 or similar connecting means. The lever motor 54 causes the lever 50 to rotate via the gears 52 and 51, thereby moving

the roll-up guide 27. In a stand-by state or a thin sheet mode, the lever 50 is held at a home position or thin sheet position indicated by a solid line in FIG. 13. In a thick sheet mode, the lever 50 is moved from the home position to a thick sheet position indicated by a dotted line in FIG. 13.

The sensor 53 turns on when the lever 50 is held at the home position. On the turn-on of the sensor 53, the controller 41 determines that the roll-up guide 27 is located at the thin sheet position. The sensor 53 turns off when the operator moves the roll-up guide 27 to the pick-up position or when the lever 50 is rotated to move the guide 27 away from the home position. The output of the sensor 53 is also sent to the controller 41.

When the roll-up guide 27 is held at the roll-up position in the rear discharge mode, the controller 41 controls the conveyance motor 43 such that the rollers 14a and 14b nip the trailing edge of the sheet S being discharged toward the first tray 25.

The operator inputs desired one of the thick sheet mode, thin sheet mode and roll-up mode on the operation panel 11. The controller 41 rotates the lever 50 via the motor 54 in accordance with the mode input on the operation panel 11 and the output of the sensor 53, so that the roll-up guide 27 is shifted in order to enlarge or reduce the



5 In operation, assume that the operator selects the thin sheet mode or the roll-up mode on the operation panel 11. Then, the controller 41 retracts the path selector 22 from the home position and causes the conveyance motor 43 forward. When the output of the sensor 53 indicates  
10 that the lever 50 is in its home position, the controller 41 causes the roll-up guide 27 to remain at the thin sheet position.

The sheet S inserted in the direction a is conveyed to the reading section 17 and then delivered to the first tray 26 in a straight position face up. After the first discharge sensor 19 has sensed the trailing edge of the sheet S, the sheet is rolled in the roll-up guide 27. As soon as the sheet 27 is rolled by a single turn, the controller 41 drives the lever motor 54 and therefore the lever 50 such that the inscribed circle increases little by little during rolling. On the elapse of a preselected period of time since the trailing edge of the sheet S moved away from the rollers 14a and 14b via the first discharge sensor 19, the controller 41 reverses the lever motor 54 by a preselected amount in order to return the lever 50

to the home position. As a result, the roll-up guide 27 returns to the thin sheet position or home position.

On the other hand, assume that the operator selects the thick sheet mode or the roll-up mode on the operation panel 11. Then, if the output of the sensor 53 indicates that the lever 50 is held at the home position, the controller 41 drives the lever motor 54 by a preselected number of pulses. The lever motor 54, in turn, rotates the lever 50 counterclockwise, as viewed in FIGS. 12 and 13, by a preselected angle away from the home position. Consequently, the roll-up guide 27 is shifted to the thick sheet position indicated by the dotted line in FIG. 13.

The sheet S is rolled by a single turn in the roll-up guide 27 on the elapse of a preselected period of time, as stated earlier. Then, the controller 41 drives the lever 50 via the lever motor 54 such that the inscribed circle increases little by little during rolling. Further, on the elapse of a preselected period of time since the trailing edge of the sheet S has moved away from the rollers 14a and 14b via the first discharge sensor 19, the controller 41 causes the lever 50 to rotate clockwise, as viewed in FIGS. 12 and 13, by a preselected angle by reversing the lever motor 54. Consequently, the roll-up guide 27 returns to the thick sheet position.

After the sheet S has been rolled up in the roll-up

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guide 27, the operator shifts the guide 27 to the previously stated pick-up position.

The conveyance motor 43 assigned to the rollers 14a and 14b and the lever motor 54 assigned to the lever 50 each are implemented by a stepping motor. It is therefore possible to determine, e.g., the length of the rolled part of the sheet S by multiplying the amount of conveyance for a single step of the stepping motor by the number of pulses (steps) fed to the motor. Therefore, there can be easily determined, e.g., the time when the sheet is rolled by a single turn in the roll-up guide 27 after the first sensor 19 has sensed the leading edge of the sheet S.

In the rear discharge mode, the controller 41 retracts the path selector 22 from the home position and causes the conveyance motor 43 to rotate forward, as stated earlier. As a result, the sheet S is driven out to the first tray 26 in a straight position face up. In the front discharge mode, the controller 41 causes the conveyance motor 43 to rotate forward while maintaining the path selector 22 at the home position. Consequently, the sheet S is reversed by the second discharge guide 21 and then driven out to the second tray 12 face down. Further, assume that the sensor 53 is in an ON state, but the roll-up mode is not selected, or that the sensor 53 is in an ON state, but the thick sheet mode is selected. Then, the

controller 41 may display on the display 32 an alarm message informing the operator of the fact that the position of the roll-up guide 27 and the operation mode do not match.

As stated above, the illustrative embodiment shifts  
5 the roll-up guide 27 stepwise in accordance with the thickness of the sheet S and the rolled length of the same. This, coupled with the fact that the space for rolling up the sheet S continuously increases, prevents the guide 27 from failing to roll up a thin sheet or causing a thick  
10 sheet to collapse and jam the guide 27.

In the illustrative embodiment, the controller 41 causes the roll-up space to be automatically enlarged or reduced in accordance with the output of the sensor 53. Alternatively, a click mechanism may be operated by hand  
15 to vary the roll-up space stepwise. Also, three or more different positions for rolling the sheet S may be assigned to the roll-up guide 27. Further, a plurality of sensors responsive to the position of the lever 50 may be used such that when the position of the roll-up guide and the mode  
20 do not match, an alarm message is displayed and/or the operation is interrupted. The illustrative embodiment is similarly applicable to the first and second embodiments.

Embodiments to be described hereinafter each include an anti-twist mechanism for preventing the sheet  
25 S being rolled in the roll-up guide 27 from twisting in

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accordance with the size of the sheet S.

#### Seventh Embodiment

FIG. 15A is a plan view showing the roll-up guide 27 representative of a seventh embodiment of the present invention and including an anti-twist mechanism. FIG. 15B is a section as seen in a direction A of FIG. 15A. FIG. 15C is a side elevation of the anti-twist mechanism. As shown, the roll-up guide 27 includes a channel 65 extending between opposite end walls 64a and 64b. A pair of anti-twist members 61 are received in the channel 65 and slidable in the widthwise direction. A pin 61a is studded on each anti-twist member 61 and protrudes to the inside of the guide 27 via an elongate slot 27a, which is formed in the bottom of the channel 65.

When the two anti-twist members 61 are slid along channel 65, the pins 61a studded on the members 61 each slide in the respective elongate slot 27a. The pins 61a therefore restrict the sheet S in the widthwise direction within the roll-up guide 27.

#### Eighth Embodiment

As shown in FIG. 16, an eighth embodiment of the present invention includes a first tray 26' intersecting the roll-up guide 27. The tray 26' includes a wire or guide rod formed with steps in accordance with the widthwise dimension of the sheet S. The tray 26', serving as the

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inlet of the guide 27 at the same time, restricts the sheet S with the above steps in the widthwise direction of the sheet S, thereby preventing the sheet S from twisting. A plurality of trays 26' each having steps corresponding to a particular sheet size may be prepared beforehand, if desired. Alternatively, a single tray 26' may be formed with various steps each corresponding to a particular sheet size.

#### Ninth Embodiment

FIG. 17A is a section showing the roll-up guide 27 representative of a ninth embodiment of the present invention and including an anti-twist member 62. FIG. 17B is a side elevation of the roll-up guide 27. As shown, the anti-twist member 62 is rotatably supported between end walls 64a and 64b of the guide 27. Pairs of blades 62a through 62d are mounted on the circumference of the anti-twist member 62, and each is located at a position corresponding to a particular sheet size. A knob 63 with a click mechanism is mounted on a shaft supporting the anti-twist member 62. By operating the knob 63, the operator is capable of causing any one of the blade pairs 62a through 62d to protrude into the guide 27 and restrict the sheet in the widthwise direction. When the operator intends to pickup the rolled sheet S, the operator positions the anti-twist member 62 such that none of the

blade pairs 62a through 62d protrudes into the guide 27.

When the sheet S is rolled up in the roll-up guide 27, the diameter of the roll depends on the length, thickness, the coefficient of friction and so forth of the sheet S. In light of this, the anti-twist member 62 should preferably be mounted such that the blades 62a through 62d can deal with a sheet having the minimum diameter when rolled up.

In the embodiments shown and described, the rollers 14a and 14b are positioned within the device upstream of the outlet. Alternatively, the nip between the rollers 14a and 14b may be exposed to the outside, i.e., located outside of the outlet, so that the trailing edge of the sheet rolled up in the roll-up guide 27 can be spaced from the casing or outlet. In such a case, the trailing edge of the sheet driven out by the rollers 14a and 14b will not remain in the casing, but will immediately reach the first tray 26 or 34.

In the embodiments shown and described, the reading section 17 constitutes image reading means. The roll-up guide 27 constitutes storing means together with associated members. The rollers 14a and 14b constitute discharging means and conveying means together with the other rollers. The belt 37 constitutes external conveying means together with associated members. The Mylar sheet

23 and first tray 26 constitute guiding means. The first  
tray 26 constitutes straight storing means. The switch  
33 constitutes sensing means. The second discharge guide  
constitutes reversal guiding means. The outside guide 35a  
5 forms a guide portion while the cylinder 35c forms a hollow  
cylindrical storing portion. The operation panel 11  
constitutes setting means. The anti-twist member 61 or  
62 plays the role of width restricting means. The pins  
61a constitute a pair of projections. The blades 62a  
10 through 62 constitute a plurality of pairs of projections.  
The second tray 12 serves as top storing means. The second  
discharge guide and rollers 15a and 15b constitute  
reversal discharging means. The path selector 22  
constitutes switching means. The shaft 29 constitutes  
15 spacing means and connecting means. The lever 50, sensor  
53 and lever motor 54 constitute roll-up space enlarging  
and reducing means.

The present invention is applicable to various kinds  
of devices of the type storing a discharged sheet in the  
20 form of a roll, spacing the trailing edge of the stored  
sheet from the device body, and allowing a person to pick  
up the rolled sheet at the position where the person is  
standing. For example, the present invention may be  
implemented as a storing device, a sheet conveying device  
25 or an image scanner or an image forming apparatus including



the sheet conveying device.

In summary, it will be seen that the present invention provides a sheet conveying device with a storage having various unprecedented advantages, as enumerated below.

(1) Roll-up storing means (roll-up guide) is connectable to the sheet conveying device such that when the storing means is shifted, the trailing edge of a sheet rolled up in the storing means is spaced from the conveying device. The trailing edge can therefore be surely pulled out of an outlet included in the conveying device. This protects the trailing edge from damage when it is picked up.

(2) Roll-up space enlarging and reducing means selectively enlarges or reduces a space for accommodating the sheet in the form of a roll in accordance with the kind of the sheet. The trailing edge of the sheet can therefore be surely pulled out of the device body. Further, a space matching with the kind of the sheet, e.g., hardness dependent on the thickness of the sheet can be guaranteed. For example, it is possible to reduce the diameter of the space as far as possible at the beginning of rolling and then increase the diameter as the diameter the sheet roll increases. This prevents a thin sheet from being folded down and prevents a thick sheet from collapsing due to

friction between it and the roll-up storing means and jamming the storing means.

5 (3) As the length of the sheet rolled up increases, the roll-up space is increased in the diametrical direction of the roll. This prevents an occurrence that friction between the roll-up storing means and the sheet increases with an increase in the diameter of the roll and causes the sheet to jam the storing means.

10 (4) External conveying means conveys the sheet driven out of the device up to the roll-up storing means. The trailing edge of the sheet can therefore be spaced from the device body and is protected from damage when the sheet is picked up.

15 (5) When the sheet is driven out toward the roll-up storing means, the conveyance is accelerated. This, coupled with the fact that the trailing edge of the sheet is spaced from the device body, prevents the trailing edge of the sheet from being damaged when the sheet is picked up.

20 (6) The roll-up storing means and discharging means, which includes roller pairs, are spaced from each other. This also protects the trailing edge of the sheet from damage.

25 (7) The roll-up storing means is movable between a roll-up position for rolling up the sheet and a pick-up

position for allowing the roll to be picked up by hand. This also protects the trailing edge of the sheet from damage. Further, the operator of the device can easily pickup the rolled sheet at an operating position, e.g.,  
5 at the front of the device.

(8) The operator shifts the roll-up storing means by gripping a knob mounted on the storing means and can therefore shift it in the same direction as the operator picks up the rolled sheet.

10 (9) Guiding means (Mylar sheet fitted on a path selector and part of a first tray) guides the sheet to the inlet of the roll-up storing means located at the roll-up position. The sheet can therefore be surely guided to the storing means and prevented from curling and jamming the  
15 device.

(10) When the roll-up storing means is brought to the pick-up position, the inlet of the storing means faces upward and allows the operator to easily pick up the rolled sheet.

20 (11) The roll-up storing means includes a Mylar sheet openably covering part of the inlet. Therefore, even when the inlet of the storing means faces downward at the roll-up position, the Mylar sheet prevents the sheet from dropping. At the pick-up position, the Mylar sheet can be readily  
25 opened to pick up the rolled sheet.

(13) The roll-up storing means is rotatable about a shaft at the upper portion of the device. The storing means is therefore movable between the roll-up position at the back of the device to the pick-up position above the device. This allows the operator, standing at the front of the device, to pick up the rolled sheet in a direction identical with the operating direction.

(15) The straight storing means includes intersection restricting means for restricting the intersection of the storing means with the roll-up storing means. This insures the space for accommodating the sheet in the roll-up storing means and thereby prevents the sheet from bending or tearing at the roll-up position.

25 (16) The device includes an upper unit and a lower

unit openably hinged to each other. The roll-up storing means slides on the intersection restricting means in interlocked relation to the opening of the upper unit, while being restricted in its intersection with the straight storing means. Therefore, when the upper unit is opened, it is possible to guarantee the roll-up space of the roll-up storing means at the roll-up position. This also prevents the sheet from bending or tearing.

(17) When sensing means responsive to the position of the roll-up storing means determines that the storing means is located at the pick-up position, a roller pair is caused to nip the trailing edge of the sheet. Therefore, when a thick, elongate sheet is discharged in a straight position, it is prevented from dropping to the floor.

(18) The device is operable in any one of a roll-up mode for rolling up the sheet in the roll-up storing means, a straight discharge mode (rear discharge mode) for discharging the sheet to the straight storing means (first tray), and a top discharge mode (front discharge mode) for discharging the sheet to top storing means (second tray). When the straight discharge mode or the roll-up mode is selected, switching means (path selector) switches a direction of conveyance to discharging means. The sheet can therefore be automatically discharged in a particular path matching with the kind of the sheet. Further, because

(19) Sensing means responsive to the position of the roll-up storing means is provided. When the operator selects the straight discharge mode on setting means, but the sensing means does not sense the roll-up storing means at the pick-up position, the straight discharge mode is inhibited. This prevents a thick sheet from being delivered to the roll-up storing means and damaged due to erroneous operation.

(21) The sheet is rolled up with its image surface positioned inside, so that an image is free from scratches when the sheet is picked up.

25 (22) The roll-up storing means has an inner periphery

having an arcuate cross-section. Therefore, the sheet entered the storing means rises along the above inner periphery and then falls due to its own weight and can therefore be easily rolled up. Because the roll-up  
5 storing means is open at its inlet and opposite ends, the operator can pick up the rolled sheet from the above or the side of the storing means without moving away from the operating position. Further, when the roll-up space is increased or decreased, the arcuate shape of the roll-  
10 up storing means allows the diameter of the above space to be readily enlarged or reduced.

(23) The roll-up storing means is rotatably supported by a shaft and includes a guide portion inclined toward the front of the device, and a hollow cylindrical  
15 storage portion contiguous with the upper end of the guide portion. The storing means rolls up the sheet, which has been reversed, at a position above the top of the device. The storing means is movable between a position for rolling up the sheet delivered into the storage portion and a  
20 position for discharging it along the outer periphery of the guide portion and storage portion. The storing means can therefore be easily, surely shifted to a front discharge position or a roll-up position. Further, the storing means does not have to be shifted from the rear  
25 to the front. Moreover, the operator can pick up the

rolled sheet at the operating position. In addition, because a person operates the device and picks up the rolled sheet at the same position, the device can be installed in a smaller space than conventional devices.

5 (24) When the device is mounted on an image forming apparatus, the trailing edge of the sheet can be surely pulled out of the apparatus without any damage. By shifting the roll-up storing means to the position above the device, the operator can easily pick up the rolled sheet  
10 at the operating position. Again, the device can be installed in a smaller space than conventional devices.

(25) In an image reading device of the type discharging the sheet, which it has read, face up, the roll-up storing means rolls up the sheet with the image  
15 surface of the sheet being positioned inside and stores in the form of a roll. This also protects the image of the sheet from scratches when the rolled sheet is picked up.

Various modifications will become possible for  
20 those skilled in the art after receiving the teachings of the present disclosure without departing from the scope thereof.

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